

Heterogeneous Integration Roadmap

Chapter 5: Automotive

TWG Chairs: Vikas Gupta (ASE), Veer Dhandapani, (NXP)

Contributors to Automotive TWG

Rich Rice	Veer Dhandapani	Venkat Sundaram	Sandeep B Sane
Shalabh Tandon	Przemyslaw Jakub Gromala	Marco Munzel	Johannes Duerr
Sven Rzepka	Rene Rongen	Hongbin Yu	Rao Tummala
Simon Stefan Franz	Thorsten Meyer	Klaus Pressel	Andreas Grassman
Abhijit Dasgupta	Wolfgang Froehlich	Vikas Gupta	Heinz Wagenonner

Chapter 5 Key Sections

- Section 4: Autonomous, ADAS and Sensing Needs
- Section 5: Data Processing for Autonomous, ADAS, Infotainment and Connectivity
- Section 6: Vehicle Electrification
- Section 7: Reliability

https://eps.ieee.org/images/files/HIR_2021/ch05_automotive.pdf

Focus Areas for Next Revision

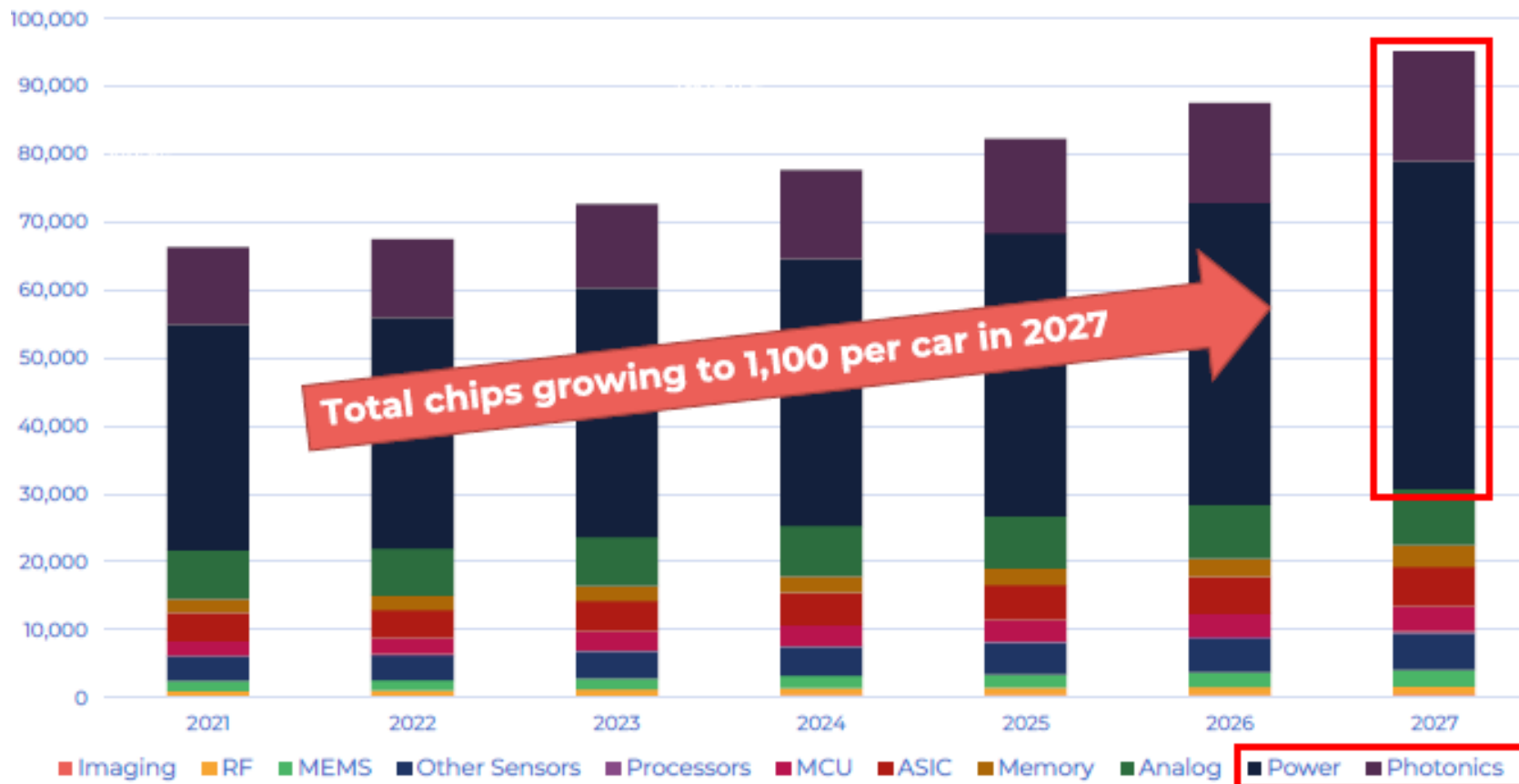
- Automotive Processors
- Sensors – Lidar, Imaging Radars
- Powertrain – Inverter, Battery Management System, On Board Charger

Semiconductors in Automotive

In 2027, over 95 billion chips will be integrated in cars.

Power & Photonics dominate, **Memory & Processors** highest growth rate

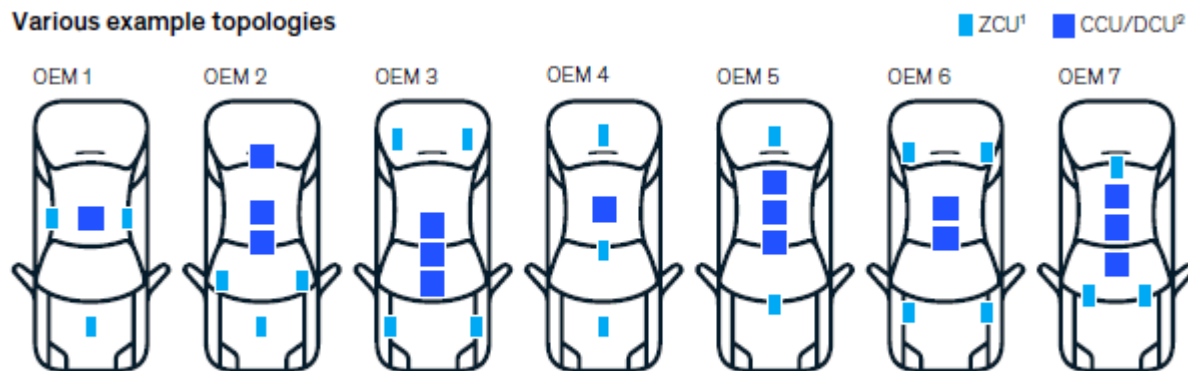
Automotive Breakdown by Device (Munits)



Source: Yole, 2023

Next Gen E/E Architecture and Compute

Various example topologies

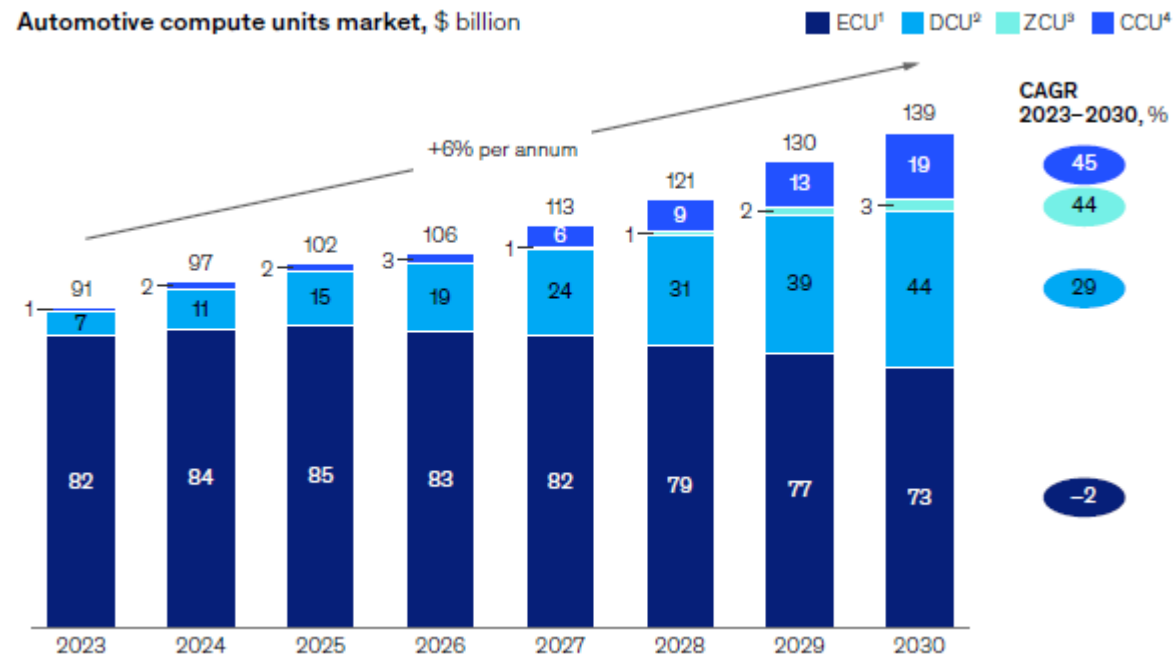


¹Zonal compute units.
²Central compute units / domain compute units.

Requirements by domain

	Zonal compute units			Domain/centralized compute units	
Domains					
Typical functionality	<ul style="list-style-type: none"> Climate control Interior/exterior lighting Seat functions 	<ul style="list-style-type: none"> Motor control Thermo management 	<ul style="list-style-type: none"> Steering Suspension Braking systems 	<ul style="list-style-type: none"> L2+: ACC,² AEB³ L3: ALKS⁴/traffic jam chauffeur 	<ul style="list-style-type: none"> Display control Audio control User applications
Compute requirements	Low-medium	Low-medium	Low-medium	High	High
	High ← Integration of functionality into zonal controller → Low				

Automotive compute units market, \$ billion



Source: McKinsey, 2023

Automotive Processor Roadmap



HETEROGENEOUS
INTEGRATION ROADMAP



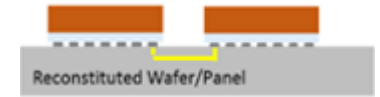
Grade 1, 2 (AEC Q100), FCBGA
(Including multi die)



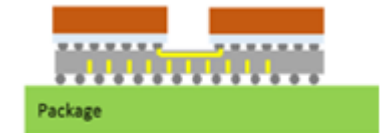
Grade 2, 3 BGA SiP Module



Including HBM Integration



Chiplets,
Memory



Advanced Si Node Acceleration, Processor Power, Increased Graphics and Memory BW

Attribute	Current	3-5 year	5+ year
Si Node	7nm (HVM), 5/4nm (Dev.)	5/4nm (HVM), 3nm (Dev.)	3/2nm (HVM), TBD
Bump Pitch	130/110um	<100um, micro-bump	<100um, micro-bump
Integration Level	PCB	Package	Die
Reliability	AEC Q100 Grade 3/2/1; AEC Q104 (SiP)		TBD
Safety	ASIL-B	ASIL-D?	



Opportunities for Cross TWG Collaboration

Autonomous, ADAS and Sensing Needs

- Processors Auto vs. HPC requirements (*HPC & Data Center TWG*)
 - Chiplets
- Sensing (*MEMS & Sensors Integration*)
 - Lidar
 - Imaging Radar

Vehicle Electrification (*Power Electronics TWG*)

- Inverter
- On Board Chargers
- DC-DC Converters, Battery Management Systems

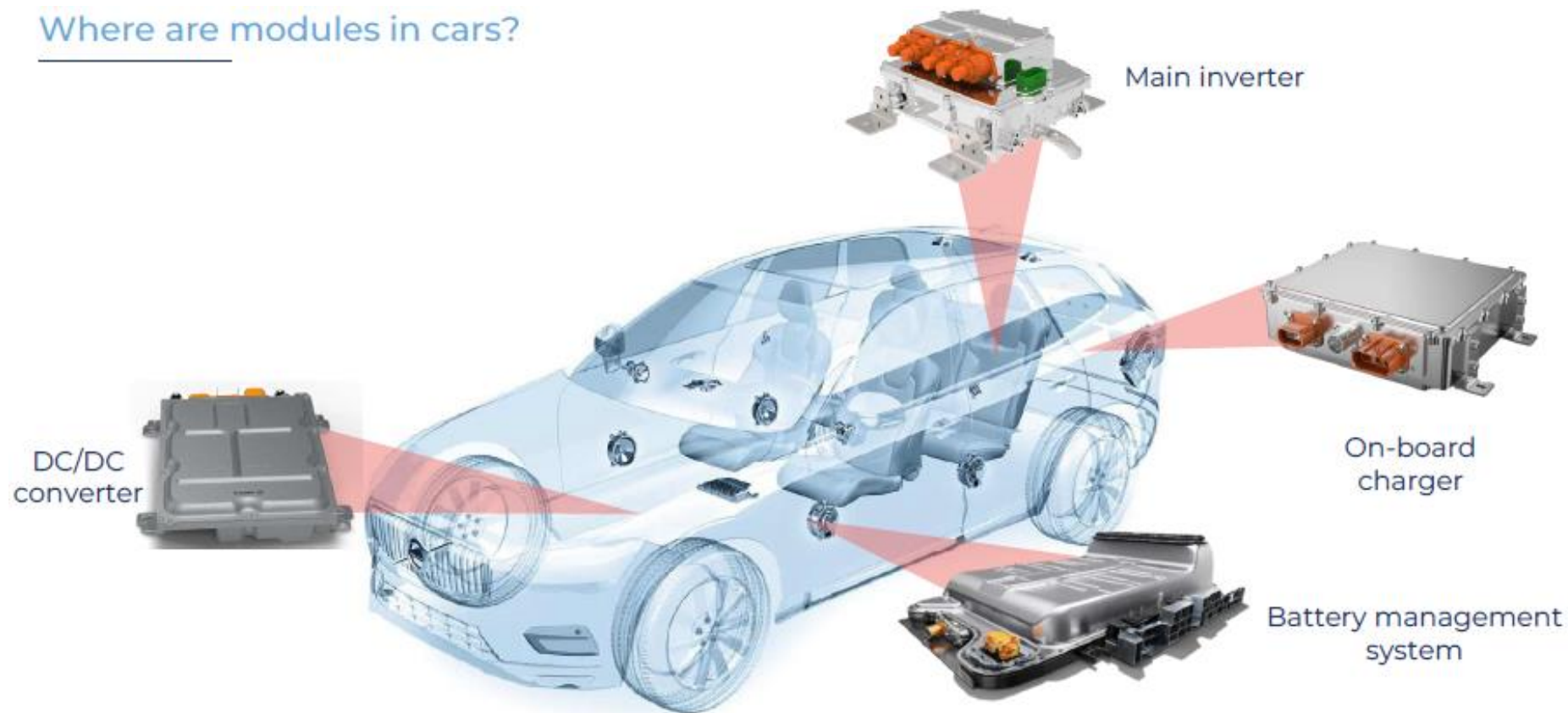
Reliability (*Reliability TWG*)

- Reliability requirements and qualification strategies for evolving use conditions



Electrification – Powertrain

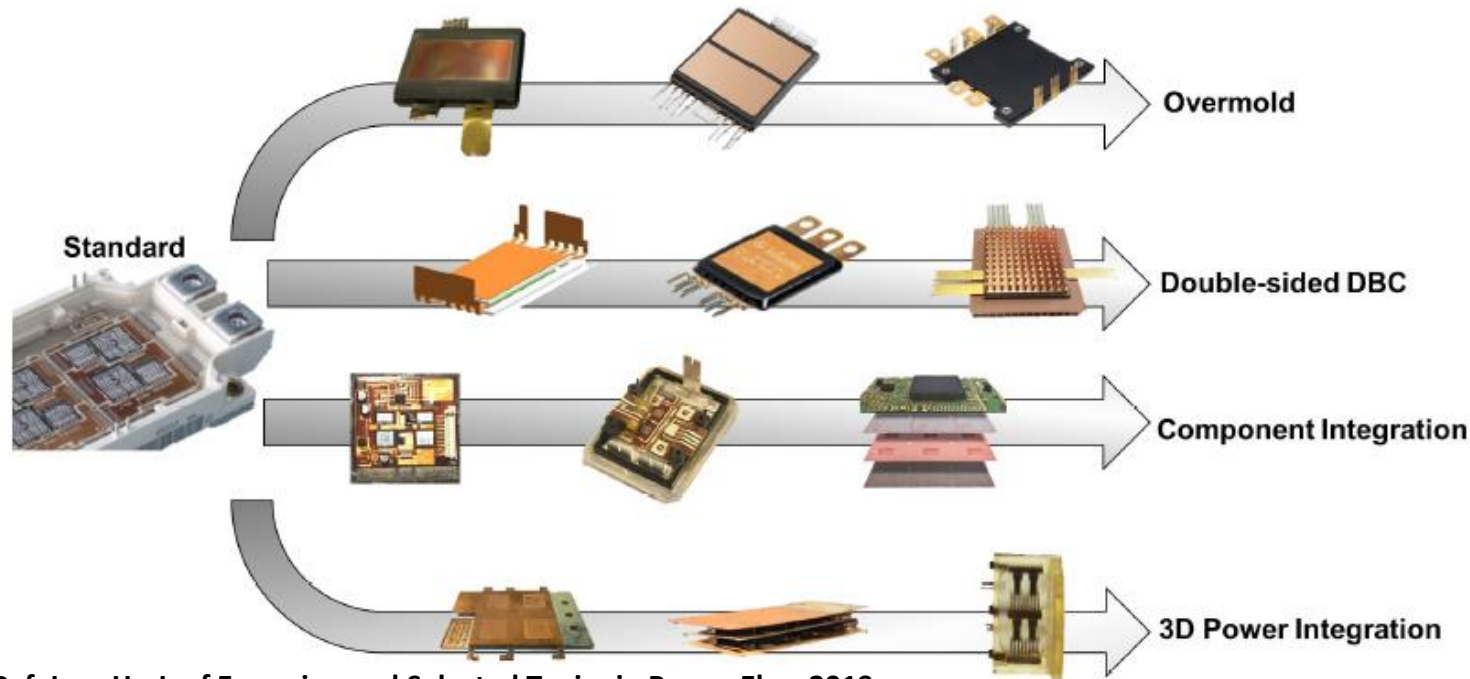
Where are modules in cars?



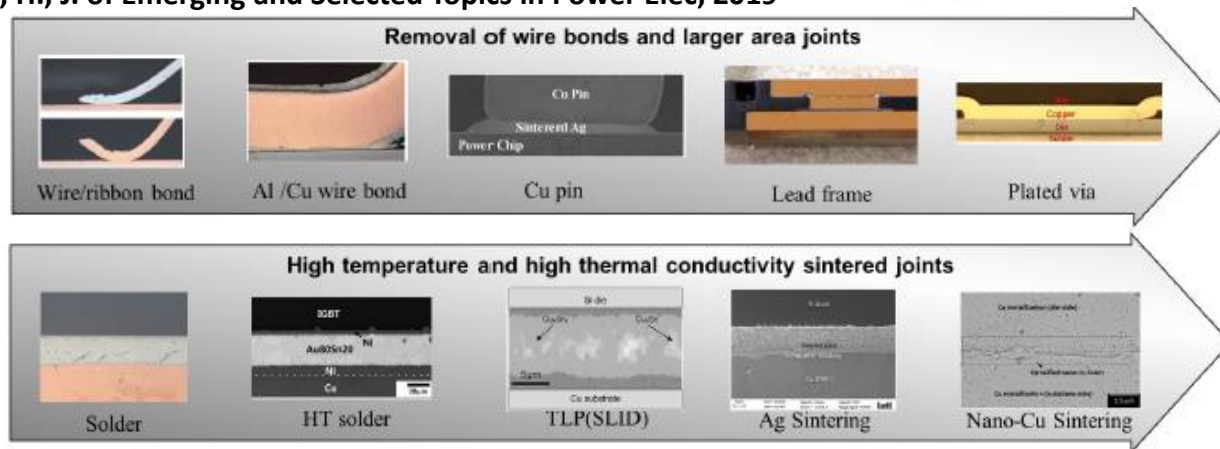
Integration and Miniaturization to improve overall efficiency

Source: Yole, 2023

Electrification and Packaging



Ref: Lee, H., J. of Emerging and Selected Topics in Power Elec, 2019



- Key Drivers
 - Lower cost \$/kW
 - Higher Power Density kW/kg
 - Smaller Size kW/L
- Enhanced modularity coupled with low inductance, low loss, improved thermal performance through advancement in package designs
- Advances in package interconnections, die-attach and substrate technologies playing a key role in package innovation and performance

Opportunities for Cross TWG Collaboration

Autonomous, ADAS and Sensing Needs

- Processors Auto vs. HPC requirements (*HPC & Data Center TWG*)
- Sensing (*MEMS & Sensors Integration*)
 - Lidar
 - Imaging Radar

Vehicle Electrification (*Power Electronics, SiP TWG*)

- Inverter
- On Board Chargers
- DC-DC Converters, Battery Management Systems

Reliability (*Reliability TWG*)

- Reliability requirements and qualification strategies for evolving use conditions



Opportunities for Cross TWG Collaboration

Autonomous, ADAS and Sensing Needs

- Processors Auto vs. HPC requirements (*HPC & Data Center TWG*)
 - Chiplets
- Sensing (*MEMS & Sensors Integration*)
 - Lidar
 - Imaging Radar

Vehicle Electrification (*Power Electronics, SiP TWG*)

- Inverter
- On Board Chargers
- DC-DC Converters, Battery Management Systems

Reliability (*Reliability TWG*)

- Reliability requirements and qualification strategies for evolving use conditions



Automotive Technical Working Group

Many Thanks for your Attention and Support